



# **Mobile Automation**

**Products and Services** 

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Specifications are subject to change without notice. Errors and omissions excepted.



## **Mobile Automation**

#### Experience | Know-how | Made in Germany

For decades, the name Jetter AG has stood for highest demands on automation solutions that are used in a wide range of industrial and mobile automation sectors.

Products and components by Jetter AG stand out thanks to their high degree of system integrity and diversity. Our in-house R&D departments (hardware and software), as well as our production plants in Germany allow us to always act in a quick and flexible manner. This, combined with a comprehensive range of Professional Services, enables us to put almost any customer request into practice.

In Industrial Automation Jetter AG is focusing on selected industries. Highly customized solutions contributing to decisive advantages in our customers' business environment put them into a position to produce state-of-the-art machines and plants.

In Mobile Automation Jetter AG develops and manufactures highly complex and robust automation concepts for controlling a wide variety of functions in municipal, firefighting, and agricultural vehicles. Thus, permanent availability of vehicles and implements is ensured.

Radical changes in industry caused by Industrie 4.0 and Internet of Things demand for future-proof solutions. Jetter AG is able to provide you with well-proven and safe systems, and to actively support you in implementing all process steps.

The product and networking philosophy of Jetter AG has always been based on the seamless integration of all automation components into production processes, such as end-of-line programming of vehicles. Jetter AG was the first company in the world to rely on consistent networking with Ethernet TCP/IP and on using common Internet protocols. A great number of systems that already now meet all essential criteria of future demands on production processes has been applied for many years by renowned customers with great success.

#### The Jetter AG mission statement:

Jetter AG is a leading provider of automation systems. Understanding your application helps us find the perfect solution in terms of functionality, sustainability and efficiency.



Jetter AG provide numerous HMIs for a wide range of requirements and applications. These devices especially distinguish themselves by their diversity of individualization options, as well as by their large number of interfaces.



## JetViewMobile 104\_\_\_\_\_

#### **Product brief**

With its compact design and rugged enclosure the JVM-104 is an ideal HMI for any application of mobile machinery.

It is equipped with a powerful controller which can be expanded by additional I/O connections, as well as by one Ethernet and one USB port. This device saves you an extra controller for many applications..

The standard operation by means of four backlit keys can be extended by a push encoder or by a touch display.

The built-in light sensor perfectly adapts the illumination of the display to the brightness of the surroundings.

#### **Product features**

- Display with built-in controller 32 bits/500 MHz
- Flexible expandability
- High connectivity
- Customizable
- Available either as a built-in or as a mounted device









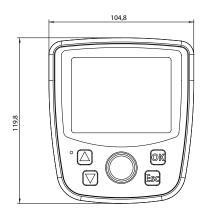
	JVM-104	
Display	3.5"TFT with LED backlight	
Display resolution and brightness	320 x 240 pixels (QVGA); 350 cd/m² (dimmable)	
CPU	iMX 35, 32 Bit, 500 MHz	
Memory: RAM - Application - Non-volatile	128 MB RAM – 512 MB Flash – 128 kB MRAM	
Programming	Graphic: JetViewSoft - Logic circuit: IEC61131-3 STX	
Operating system	WinCE 6.0	
Operating voltage	DC 8 32 V	
Operating/storage temperature	-20 +65 °C/-30 +85 °C	
Ports and interfaces		
■ CAN	1 (2) CANopen®, SAE J1939, ISOBUS 11783 (option: 2 interfaces)	
■ USB	1 (option)	
■ Ethernet	1 (option)	
Control elements	Up to 8 Membrane pushbuttons, backlit	
	1 Digipot - pushbutton function (option)	
	1 Touch display (option)	
Signaling	1 Buzzer 83 dB/10 cm/2670 Hz	
Max. number of inputs/outputs	6 (option: enclosure with Deutsch-DT connectors)	
■ Inputs (option)		
Analog	0 15 V/0 20 mA, can be configured individually, resolution: 12-bit, input impedance: $50~k\Omega$ , load resistor: $120~\Omega$ 2 Alternative usage:  Digital input active-high, input impedance $50~k\Omega$ Frequency input 0.1 10 kHz, period > 1 $\mu$ s, input impedance $20~k\Omega$ Counting input 0.1 Hz - 10 kHz, counting range $32~bits$	
Outputs (option)		
H-bridge	<ul> <li>2.5 A; peak current 5 A (500 ms)</li> <li>Alternative usage: <ul> <li>4x PWM 2.5 A; 100 Hz 1 kHz, diagnostics capability</li> <li>4x digital output 2.5 A , high-side, diagnostics capability</li> <li>4x digital input active-high, NAMUR support, 8.2 V at 1 kΩ pull-up</li> </ul> </li> </ul>	
Max. permitted total current	12 A fully equipped with I/Os	
Degree of protection	IP65 front/IP65 rear with rear-side Ethernet/USB port: IP20	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	

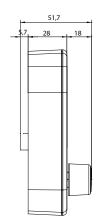
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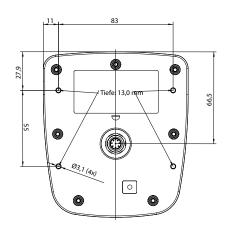
# JetViewMobile 104\_\_\_\_\_

## Dimensional drawing

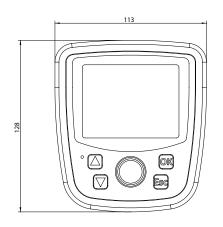
### Stand-alone assembly model

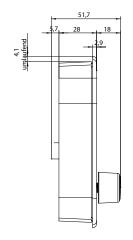


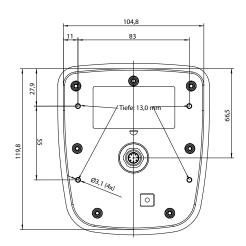




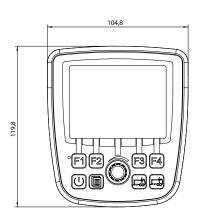
#### Flush mount model

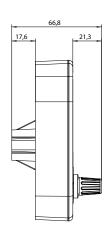


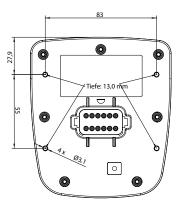




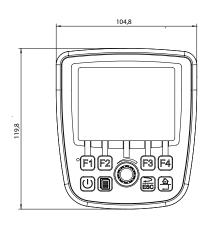
#### Model with Deutsch connector

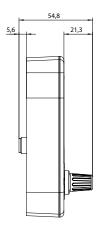


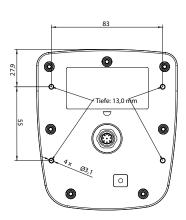




#### Model with M12 screw-type connector



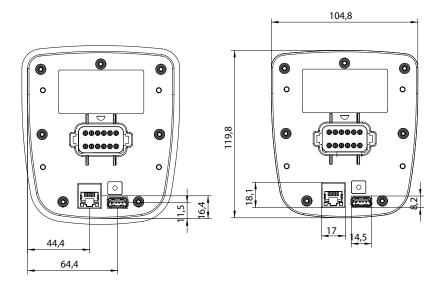




# JetViewMobile 104\_\_\_\_\_

### Dimensional drawing

#### Ethernet and USB interfaces



#### Accessories

Dash mounts by RAM Mount



## Connector pinout

JVM-104 - Basic version	
M12 - 8-pin, e.g. Lumberg RKCN 8/9	
Power supply - Logic unit - 2 A	1
n.c.	2
Power supply ON	3
n.c.	4
CAN1-L	5
Ground	6
CAN1_H	7
n.c.	8

JVM-104 with I/O expansion	
Deutsch DT06-12S	
Ground	1
Output 1	2
Output 2	3
Output 3	4
Output 4	5
Power supply - Logic unit - 2 A	6
Power supply of power outputs 10 A	7
Power supply ON	8
CAN1_L	9
CAN1_H	10
Analog input 1	11
Analog input 2	12

USB host interface, USB 2.0 Ethernet port, RJ45 jack

JVM-104 with I/O expansion and second CAN bus	
Deutsch DT06-12S	
Ground	1
CAN2_L	2
CAN2_H	3
Output 3	4
Output 4	5
Power supply - Logic unit - 2 A	6
Power supply of power outputs 10 A	7
Power supply ON	8
CAN1_L	9
CAN1_H	10
Analog input 1	11
Analog input 2	12

## JetViewMobile 407B\_\_\_\_\_

#### **Product brief**

With its elegant and high-quality design, the JVM-407B HMI is a standout product and can be supplied both as flush mount or stand-alone assembly device.

Right and left of the 7" display, 10 LEDs have been arranged, which, thanks to an integrated controller within the HMI, can be directly operated by the user. This way, they can also be used as warning and control lights for cars; they even allow for the JVM-407B to be used as a fully-fledged dashboard.

The integrated controller of the HMI is equipped with multi-purpose interfaces and can therefore be used as a powerful master controller for medium-size systems. A video input allows for integrating a rear view camera.

The HMI is operated via four high-value backlit keys, as well as a digipot used as pushbutton. The acoustic signaling device produces an alarm loud enough to be heard even in noisy surroundings. A USB port at the front side allows for simple data interchange in the field.

#### **Product features**

- Display with built-in controller 32 bits/500 MHz
- 3 CAN ports, Ethernet, SD card and front-side USB port
- Video input
- Integrated car LED
- Elegant and high-value design
- Available either as a built-in or as a mounted device



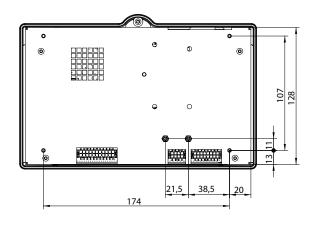
	JVM-407B	
Display	7"TFT with LED backlight	
Display resolution and brightness	800 x 480 pixels (WVGA); 300 cd/m² (dimmable)	
CPU	iMX 35, 32 Bit, 500 MHz	
Memory: RAM - Application - Non-volatile	128 MB RAM – 512 MB Flash – 128 kB MRAM	
Programming	Graphic: JetViewSoft - Logic circuit: IEC61131-3 STX	
Operating system	WinCE 6.0	
Operating voltage	DC 8 32 V	
Operating/storage temperature	-20 +65 °C/-30 +85 °C	
Ports and interfaces		
■ CAN	3 CANopen®, SAE J1939, ISOBUS 11783	
■ USB	1 front panel	
SD memory card	1 rear panel	
■ Ethernet	1	
■ CVBS	1	
Control elements	4 Keys, backlit	
	1 Digipot used as pushbutton, backlit	
Signaling	1 Buzzer	
	10 LEDs of customized design	
Inputs (option)		
■ Digital	10 Switch input for LEDs, supply by Ub is possible	
	5 Digital input active-high, input impedance 43 $k\Omega$	
Outputs (option)		
■ Digital	1 Peak current 3 A	
RTC	Yes; replaceable battery	
Degree of protection	Flush mount model: IP65 front/IP20 rear Stand-alone assembly model: IP65 front/IP54 rear	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	

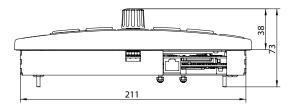
Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

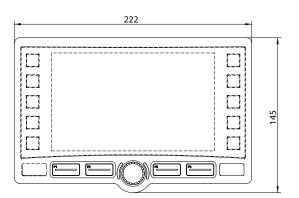
## JetViewMobile 407B\_\_\_\_\_

### Dimensional drawing

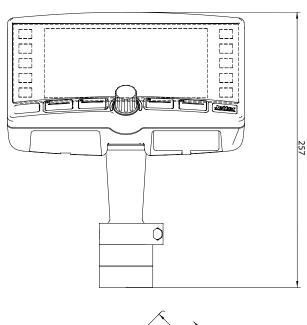
#### Flush mount model

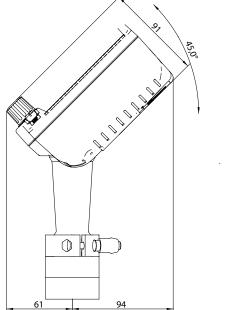






### Stand-alone assembly model





## Connector pinout

JVM-407B	
Molex Microfit 3.0 - 22-pin	
Power supply	1
Power supply ON	2
Output 1	3
LED 2	4
LED 4	5
LED 6	6
LED 8	7
LED 10	8
Input 2	9
Input 4	10
Ground	11
Power supply	12
Output 1	13
LED 1	14
LED 3	15
LED 5	16
LED 7	17
LED 9	18
Input 1	19
Input 3	20
Input 5	21
Ground	22

JVM-407B	
Molex Microfit 3.0 - 8-pin	
Supply voltage DC 12 V for the camera	1
Video signal +	2
Shield	3
Ground	4
Video signal -	5
Ground	6
Video signal -	7
n.c.	8

USB host interface, USB 2.0 Ethernet port, RJ45 jack SD card slot, rear side

JVM-407B	
Molex Microfit 3.0 - 16-pin	
CAN1_H_IN	1
CAN1_Term	2
CAN1_L_OUT	3
CAN2_L_IN	4
CAN2_H_OUT	5
CAN3_H_IN	6
CAN3_Term	7
CAN3_L_OUT	8
CAN1_L_IN	9
CAN1_U_OUT	10
CAN2_H_IN	11
CAN2_Term	12
CAN2_L_OUT	13
CAN3_L_IN	14
CAN3_H_OUT	15
Shield	16

## JetViewMobile 507B \_\_\_\_\_

#### **Product brief**

The HMI JVM-507B is equipped with a 7" display and 12 backlit keys with symbols printed to customer's wishes. The keys have been arranged right and left of the display. As an option, the HMI can be supplied with a resistive touch screen. This way, highly flexible and comprehensive operating concepts can be implemented. The HMI has been designed for installation in a double DIN slot in the dashboard.

The integrated controller of the HMI is equipped with multi-purpose interfaces and can therefore be used as a powerful master controller for medium-size systems. Four video inputs allow for establishing high-level monitor applications.

A light sensor allows for automatically adjusting to display brightness and key backlighting. The acoustic signaling device produces an alarm loud enough to be heard even in noisy surroundings.

#### **Product features**

- Display with built-in controller 32 bits/500 MHz
- Keys to be labeled
- 2 CAN ports, Ethernet, microSD card and USB port
- 4 video inputs
- Rugged aluminum front panel

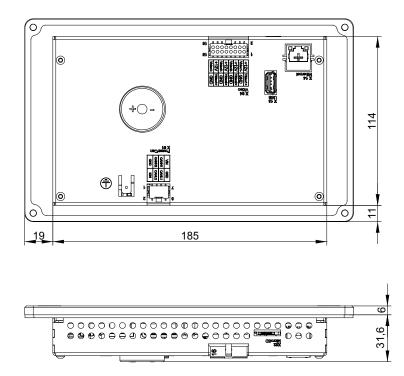


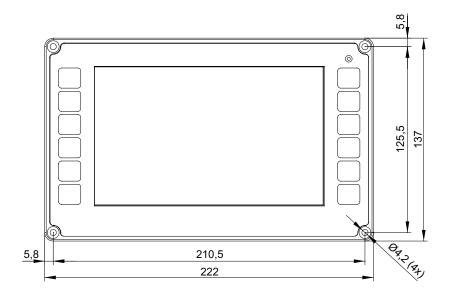
	JVM-507B	
Display	7"TFT with LED backlight	
Display resolution and brightness	800 x 480 pixels (WVGA); 300 cd/m² (dimmable)	
CPU	iMX 35, 32 bit, 500 MHz	
Memory: RAM - Application - Non-volatile	128 MB RAM – 512 MB Flash – 128 kB MRAM	
Programming	Graphic: JetViewSoft - Logic circuit: IEC61131-3 STX	
Operating system	WinCE 6.0	
Operating voltage	DC 8 32 V	
Operating/storage temperature	-20 +65 °C/-30 +85 °C	
Ports and interfaces		
■ CAN	2 CANopen®, SAE J1939, ISOBUS 11783 - 125 kB/s up to 1MB/s	
■ USB	1	
<ul><li>microSD card</li></ul>	1	
■ Ethernet	1	
<ul><li>CVBS</li></ul>	4	
Control elements	12 Backlit keys with symbols printed to customer's wishes	
	1 Resistive touch (optional)	
Signaling	1 Buzzer	
RTC	Yes, buffering with Goldcap (about 1 week of typical capacity)	
Degree of protection	Flush mount model: IP65 front/IP20 rear Stand-alone assembly model upon request	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# JetViewMobile 507B \_\_\_\_\_

## Dimensional drawing





## Connector pinout

JVM-507B	
Molex Microfit 3.0 - 16-pin X64	
Video signal 1+	1
Supply voltage 12 V, camera 1	2
Ground	3
Video signal 1-	4
Video signal 2+	5
Supply voltage 12 V, camera 2	6
Ground	7
Video signal 2-	8
Video signal 3+	9
Supply voltage 12 V, camera 3	10
Ground	11
Video signal 3-	12
Video signal 4+	13
Supply voltage 12 V, camera 4	14
Ground	15
Video signal 4-	16

X13 USB host interface, USB 2.0 X14, Ethernet port, RJ-45 jack X62 microSD card slot, rear side

JVM-507B		
Molex Microfit 3.0 - 8-pin X61		
Ground	1	
Ignition ON	2	
CAN2_H	3	
CAN2_L	4	
CAN1_H	5	
CAN1_L	6	
Power supply	7	
Ground	8	

# Multi-display controller \_\_\_\_\_





## JetControlMobile 630

#### **Product brief**

The multi-monitor controller JCM-630 combines outstanding video features with high-performance HMI and PLC disciplines in one system.

A powerful 32-bit CPU with 800 MHz clock rate forms the heart of the automation functions. Four CAN interfaces, Gbit Ethernet connectivity, USB, LIN, and RS232 offer high connectivity for complex architectures.

The visualization takes place on 2 displays via LVDS interfaces with one connector per display being sufficient. A host of supported display formats and configurations allow a high flexibility in the arrangement of the screens.

6 camera images from 8 camera channels can be processed simultaneously in one FPGA with minimal latency. The images can be freely scaled, cut, positioned or superimposed with graphic and text elements. This way, operating concepts exceeding the level of integration into modern middleclass cars can be physically established in special-purpose vehicles with moderate application expense.

The IEC-61131-3-compliant programming language STX, a plug-in for programming in C, and scalable vector graphics support by JetViewSoft offer a highly efficient workflow for control and visualization. The JCM-630 is available with ISOBUS stack.

#### **Product features**

- Powerful PLC with high connectivity
- Excellent HMI features on two displays
- Free positioning, size adjustment and scaling of 6 camera images
- Integrated programming environment to IEC-61131-3 JetSym and JetViewSoft
- Can be updated via USB flash drive

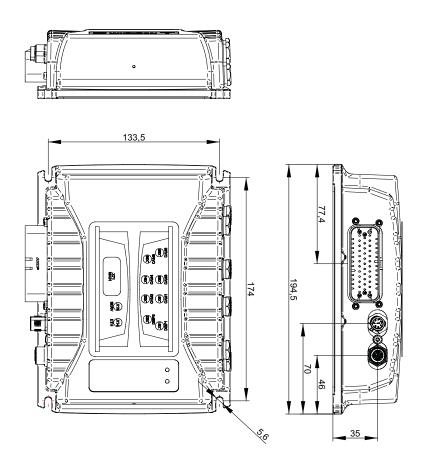


	JetControlMobile 630		
CPU	iMX 6, 32-bit, 800 MHz		
Memory: RAM - Application - Non-volatile	1 GB 4 GB eMMC flash		
Co-CPU ( CAN3,4 / Watchdog)	120 MHz, 128 KB 512 KB flash		
Graphics programming	JetViewSoft - Logic circuit: IEC61131-3 STX		
Controller programming	JetSym - Logic circuit: IEC61131-3 STX		
Operating system	WinCE 2013		
Power management	Boot-up duration < 10 s (until application screen appears)		
Operating/storage temperature	-30 +75 °C/-40 +85 °C		
Ports and interfaces			
■ FPD-LINKII	2 Display, display power supply, CAN		
■ CAN	4 CANopen®, SAE J1939, ISOBUS 11783, 125 kB/s through 1 MB/s		
■ USB	1		
Ethernet	1 (option)		
CVBS cameras	8 6 of them can simultaneously be displayed (camera supply included)		
RS-232	2 (option)		
• LIN	1 (option, uses DI3)		
Inputs	1 Camera supply		
Inputs, digital	1 Ignition 3 Digital input active-high, input impedance 43 kΩ		
Outputs, digital	2 Peak current 3 A		
RTC	Yes, various backup modes, battery included		
Degree of protection	IP65		
Vibration	DIN EN 60068-2-64, Cat. 2		
Shock	DIN EN 60068-2-64, 30 g		
Protection against polarity reversal	Yes		

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# JetControlMobile 630 \_

## Dimensional drawing



## Connector pinout

JCM-630	
35-pin male connector	
Ignition, U <sub>ian</sub> (terminal 15)	1
GND, battery - (terminal 31)	2
UB, battery + (terminal 30)	3
n.c. (not connected)/option: CAN3 L	4
CAN2 L	5
CAN1 L	6
n.c./option: CAN4 L	7
n.c./option: CAN4 H	8
GND for RS-232 (COM2)	9
GND (supply) for CAM8	10
DO1	11
DO2	12
Supply DC 12 V DC 12 V/24V for CAM8	13
Video input for CAM7	14
Video input + for CAM8	15
n.c./option: CAN3 H	16
CAN2 H	17
CAN1 H	18
GND	19
GND	20
GND (supply) for CAM7	21
GND	22
Shield	23
Power supply DC 12 V/24 V for CAM7	24
Video input + for CAM7	25
Video input for CAM8	26
RS-232TX (COM2)	27
RS-232 RX (COM2)	28
DI1	29
Output power camera (OUT)/DO3 to 3 A	30
Power consumption camera (IN: DC 12 V/24 V)	31
DI2	32
n.c./option: DI3	33
Shield	34
Shield	35

JCM-630		
M12 male connector - Service port 1		
USB signal VCC5 + I/O	1	
USB signal DATA -	2	
USB signal DATA +	3	
- (do not connect)	4	
Screen for USB	5	
RS-232 RX (COM1)	6	
RS-232TX (COM1)	7	
GND	8	

JCM-630		
M12 female connector - Service port 2 (Gbit Ethernet)		
D1 +	1	
D1 -	2	
D2 +	3	
D2 -	4	
D4 +	5	
D4 -	6	
D3 -	7	
D3 +	8	

JCM-630		
M12 female connector - WLVDS 1 2 - OUT		
24-V supply	1	
GND (supply)	2	
GND (supply)	3	
LVDS 1 2 +	4	
CAN1 Low	5	
LVDS12 -	6	
24-V supply	7	
CAN1 High	8	

JCM-630	
M12 socket - CAM1 CAM6	
Video input - for CAM1 6	1
GND (supply)	2
Video input + for CAM1 6	3
Supply DC 12 V / 12 V for CAM1 6	4
GND (supply)	5

# JetViewMobile MT101 | M043 \_

#### **Product brief**

The outstanding feature of the new monitor generation JVM-Mxxx is its brilliant displays of appealing design which are also readable in bright sunlight.

Coming as mere monitors of 4.3 to 10.1", the devices are low-size enough to be installed even in small spaces.

The corresponding high-performance ECU JCM-630 does not only establish all connections with the mobile machine, but it also provides two monitors with operating parameters by single-cable technology.

Thanks to its multi-kernel processors, its four CAN, LIN, Gbit Ethernet connections, and its eight camera inputs, the JCM-630 is fit for any kind of today's and tomorrow's operating philosophy.

#### **Product features**

- Brilliant displays readable in bright sunlight
- Slim, modern design
- Single-cable connection to JCM-630
- PCAP can be integrated
- Mounting: VESA/RAM, flush mounting



	JVM-N	MT101	JVM-M043	
Display		10.1"TFT with LED backlight	4.3"TFT with LED backlight	
Resolution		1024 x 600 pixels	480 x 272 pixels	
Brightness		500 cd/m2( dimmable)	800 cd/m2( dimmable)	
Viewing angle (h/v, u/d)		160°;160°	150°; 150°	
Contrast		500:1	300:1	
Control elements	1	PCAP touchscreen (option)		
	4	Keys, backlit (option)		
	1	Push encoder, backlit (option)		
Signaling	1	Buzzer 85 db (option)		
Ports and interfaces				
- FPD-LINKII	1	Display, display power supply, CAN		
- CAN	1	CANopen®; 125 kB/s to 1MB/s		
- External keyboard, rotary,	10 ch.	h. Matrix keyboard, switches, push encoder(option)		
Programming	Via JCM-630 series Graphic: JetViewSoft - Logic circuit: IEC61131-3 STX			
Operating voltage	DC 8 32 V			
Operating/storage temperature	-20 +65 °C/-30 +85 °C			
Degree of protection	"Open frame" model: IP23 front/IP20 rear			
	Stand-alone assembly model: IP54 front/IP54 rear			
Vibration	DIN EN 60068-2-64, Cat. 2			
Shock	DIN EN 60068-2-64, 30 g			
Protection against polarity reversal	Yes			

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

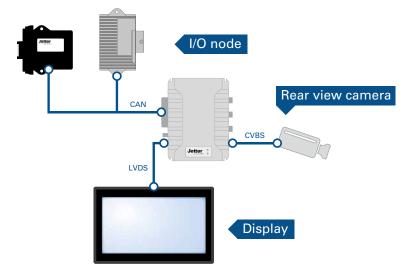
## Application Examples \_\_\_\_\_

#### Flexible in application

- Based on different display options, the cost of various configurations in a vehicle can be weighted. Displays of different sizes can be easily exchanged thanks to their vector graphics support. The visualization remains the same for all variants
- Superimposition of graphic elements or text information on video images facilitates intuitive operation. The optional PCAP multi-touch interface allows for unlimited ease of operation
- Several identical displays with identical contents can be cascaded - ideal for vehicles with multiple operator consoles
- The optional ISOBUS stack enables powerful implement control. What's more, its video integration compensates for the limited camera performance of ISOBUS.

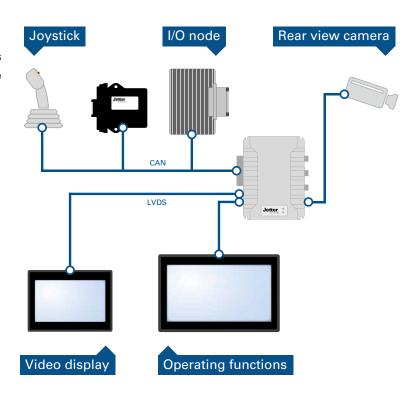
#### Application example # 1

Typical basic equipment for a municipal vehicle with complete body control and integration of the rear view camera into the operating concept.



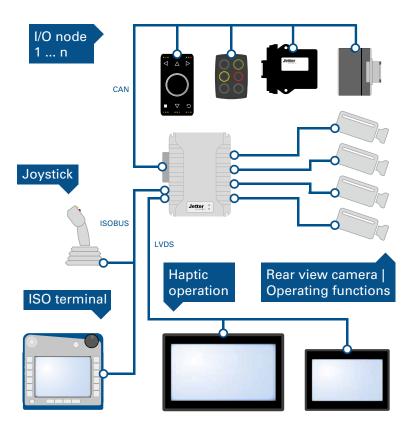
#### Application example # 2

Extended range of functions with 2 displays for splitting up the visualization of machine functions and video camera.



#### Application example #3

Powerful ISOBUS ECU with extended video performance for visual monitoring of a production chain in an agricultural self-propelled vehicle.





Controllers of the JetControlMobile series can best meet the special demands made on mobile automation. Their pre-eminent trait is the combination of ultimate ruggedness, high and scalable CPU performance and the ability to implement individual customer requirements. The controllers can directly be built into the vehicle without a control cabinet being needed. This is space-saving and therefore allows for flexible installation.



## JetControlMobile 521\_\_\_\_

#### **Product brief**

The JCM-521 controllers are fully modular. They have been designed for control systems exacting high-level requirements on flexibility and connectivity.

The controllers consist of a main board and of MX modules which are add-ons providing various functions. The main board is equipped with a powerful CPU and FPGA. Depending on the desired configuration, it can be equipped with up to 6 MX modules in any combination. Fully equipped, it offers up to 48 I/O connections. This way, I/O allocation can precisely be adjusted to any application object.

An optional diagnostics display with controls features production data display, diagnostics and configuration on the spot without additional supporting devices such as PC or testing devices still being needed.

#### **Product features**

- 32-bit controller, 500 MHz
- Programming to IEC 61131-3 STX or in C/C++
- Modular I/O configuration for high flexibility
- CAN, USB, LIN, and RS232 port for high connectivity.
- Built-in controls with graphic display



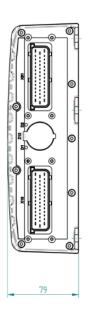
	JetControlMobile 521		
CPU	ARM 11, 32-bit, 500 MHz		
Memory: RAM - Application - Non-volatile	128 MB RAM – 512 MB Flash – 128 kB MRAM		
Peripherals	FPGA		
Programming	IEC 61131-3 STX, C/C++	+	
Operating system	WinCE 6.0		
Operating voltage	DC 8 32 V, load volta	ge isolated	
Operating/storage temperature	-40 +85 °C		
Ports and interfaces			
■ CAN	2 (optionally more)	125 kB/s to 1 MB/s CANopen®, SAE J1939, ISOBUS 11783 Jetter CAN-Prim for customer-specific proprietary protocols	
■ Ethernet	Option; up to 100 Mbit/s		
■ USB	1 (optionally more), host and client		
■ RS232	1		
■ LIN	1		
Operation and diagnostics (optional)	1 LCD graphics display 6 LEDs red, green 3 Keys		
RTC	Option		
Maximum amount of inputs/outputs*	48		
Maximum number of MX modules	6		
Max. permitted total current	40 A		
Safety relay in the load circuit	Yes, PWM outputs can be disabled		
Degree of protection	IP65		
Vibration	DIN EN 60068-2-64, Cat. 2		
Shock	DIN EN 60068-2-64, 30 g		
Protection against polarity reversal	Yes		

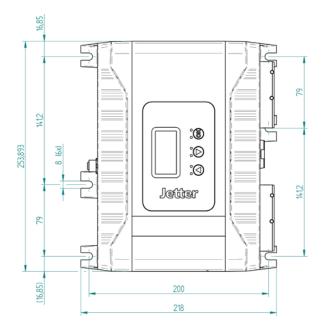
<sup>\*</sup> Number of I/O connections depends on configuration with MX modules.

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# JetControlMobile 521\_\_\_\_\_

## Dimensional drawing







X10	
and up to 2 MX modules  Tyco A	mpseal
Supply of power outputs	1
MX2-1	2
MX2-4	3
MX2-7	4
MX1-2	5
MX1-5	6
MX1-8	7
CAN1 L input	8
CAN1 H input	9
RS-232TX	10
RS-232 RX	11
Ground - Logic circuit	12
Ground - Logic circuit	13
Ground - Power outputs	14
Supply of power outputs	15
MX2-2	16
MX2-5	17
MX2-8	18
MX1-3	19
MX1-6	20
CAN1 L output	21
CAN1 H output	22
Emergency OFF signal	23
Emergency OFF PWR	24
LIN1	25
CONFIG	26
Power supply - Logic unit	27
Ground - Power outputs	28
Supply of power outputs	29
MX2-3	30
MX2-6	31
MX1-1	32
MX1-4	33
MX1-7	34
CAN2 L	35
CAN2 H	36
Ignition ON	37
TBC OFF	38
Power supply - Logic unit	39
Power supply - Sensors	40
Power supply - Sensors	41
Ground - Power outputs	42

X61	
4 MX modules each   Tyco Ampsea	al
Supply of power outputs	1
MX6-1	2
MX6-4	3
MX6-7	4
MX5-2	5
MX5-5	6
MX5-8	7
MX4-3	8
MX4-6	9
MX3-1	10
MX3-4	11
MX3-7	12
Ground - Logic circuit	13
Ground - Power outputs	14
Supply of power outputs	15
MX6-2	16
MX6-5	17
MX6-8	18
MX5-3	19
MX5-6	20
MX4-1	21
MX4-4	22
MX4-7	23
MX3-2	24
MX3-5	25
MX3-8	26
Power supply - Logic unit	27
Ground - Power outputs	28
Supply of power outputs	29
MX6-3	30
MX6-6	31
MX5-1	32
MX5-4	33
MX5-7	34
MX4-2	35
MX4-5	36
MX4-8	37
MX3-3	38
MX3-6	39
Power supply - Sensors	40
Power supply - Sensors	41
Ground - Power outputs	42

## JetControlMobile 511

#### **Product brief**

The semi-modular compact controller JetControlMobile 511 is based on the modular JCM-521 series. Due to its vast I/O capacity featuring high-performance H-bridges, PWM outputs, flexibly applicable inputs and high total ampacity, even its basic configuration is already sufficient for numerous applications. Besides hydraulic actuators, it can even directly control electric motors. Extensibility by two MX modules allows for easily adjusting to a great variety of functions and applications.

Besides standard ports and interfaces, the JCM-511 is equipped with inputs apt for NAMUR, as well as with a LIN port. This way, it can be integrated into almost any systems architecture.

The high-level language STX to IEC 61131-3 lets you implement virtually any control task. Programming in C/C++ is possible, too.

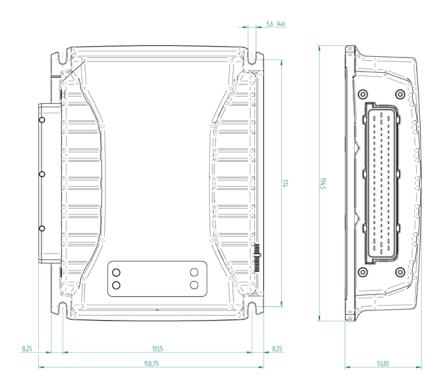
- 32-bit controller, 500 MHz
- Programming to IEC 61131-3 STX or in C/C++
- Partially modular I/O configuration for high flexibility
- CAN, USB, LIN and RS232 port for high connectivity.
- Compact design



	JetControlMobile 511	
CPU	ARM 11, 32-bit, 500 MHz	
Memory: RAM - Application - Non-volatile	128 MB RAM – 512 MB Flash – 128 kB MRAM	
Peripherals	FPGA	
Programming	IEC 61131-3 STX, C/C++	
Operating system	WinCE 6.0	
Operating voltage	DC 8 32 V, load voltage isolated	
Operating/storage temperature	-40 +85 °C	
Ports and interfaces		
■ CAN	125 kB/s to 1 MB/s  2 CANopen®, SAE J1939, ISOBUS 11783  Jetter CAN-Prim for customer-specific proprietary protocols	
■ USB	1	
■ RS232	1	
• LIN	1	
Ethernet	1 (option)	
Operation and diagnostics	2 status-LEDs	
RTC	Option	
Max. number of inputs/outputs	40	
Inputs (basic design)		
<ul><li>Analog</li></ul>	resolution: 12-bit, input impedance: 75 kΩ, load resistor: 120 Ω  8 Alternative usage:  NAMUR input with a bias voltage of 8.2 V  Digital input active-high, input impedance 50 kΩ  Frequency input, 0.1 10 kHz, period > 1 μs	
<ul><li>Digital</li></ul>	Active-high, input impedance 50 kΩ  8 Alternative usage: ■ Frequency input, 0.1 10 kHz, period > 1 μs	
Outputs (basic configuration)		
■ PWM	3.5 A; current control 1 %; 10 Hz 1 kHz  4 Alternative usage:  Digital output 3.5 A high-side	
■ H-bridge	15 A; 10 Hz 1 kHz  2 Alternative usage:  4 x PWM 10 Hz 1 kHz, 15 A  4 x digital output 15 A high-side  4 x digital output 15 A low-side	
Maximum number of MX modules (expansion modules)	2 Up to 8 inputs/outputs per MX module	
Power supply - External sensors	5 V or 10 V, can be toggled via software configuration	
Max. permitted total current	30 A, temporarily 60 A	
Safety relay in the load circuit	Yes, PWM outputs can be disabled	
Diagnostics	Total current monitoring, protection against polarity reversal, overload and no-load detection, all I/Os are protected against short circuit to GND and Ub	
Degree of protection	IP65	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	

# JetControlMobile 511 \_\_\_\_\_

# Dimensional drawing



JCM-511   70-pin AMPTyco 963484     H-bridge A1	1
Ignition ON 2 Power supply - Logic unit and external circuit 3 CAN1-L 4 CAN1-H 5 PWM3 6 PWM1 7 PWM2 8 PWM4 9 USB CNX 10 USB Dp 11	1
Power supply - Logic unit and external circuit         3           CAN1-L         4           CAN1-H         5           PWM3         6           PWM1         7           PWM2         8           PWM4         9           USB CNX         10           USB Dp         11	1
CAN1-L 4 CAN1-H 5 PWM3 6 PWM1 7 PWM2 8 PWM4 9 USB CNX 10 USB Dp 11	1
PWM3 6 PWM1 7 PWM2 8 PWM4 9 USB CNX 10 USB Dp 11	1
PWM1       7         PWM2       8         PWM4       9         USB CNX       10         USB Dp       11	1
PWM2         8           PWM4         9           USB CNX         10           USB Dp         11	1
PWM4         9           USB CNX         10           USB Dp         11	1
USB CNX 10 USB Dp 11	1
USB Dp 11	1
USB DM 11	2
COD DIVI	
Output - Reference voltage	3
Analog input 1	4
Analog input 2	 5
Analog input 3	6
Analog input 4	7
Analog input 5	8
Analog input 6	9
Analog input 7 20	0
Analog input 8 2	1
Supply of power outputs 22	2
Ground 23	3
H-bridge B1 24	4
H-bridge A2 25	5
Ground 26	6
Input for release relay 27	7
CAN2-L 28	8
CAN2-H	9
Digital input 1 30	0
Digital input 2	1
Digital input 3	2
Digital input 4	3
Digital input 5	4
Digital input 6 39	5
Digital input 7	6
Digital input 8	7
RS232-TX 38	8
Ground 39	9
Ground 40	0

JCM-511   70-pin AMPTyco 963484	
MX6-1	41
MX6-2	42
MX6-3	43
MX6-6	44
MX6-7	45
Supply of power outputs	46
Ground	47
H-bridge B2	48
Switched power for external devices	49
Power supply - Release relay	50
n.c.	51
n.c.	52
MX5-2	53
MX5-3	54
MX5-8	55
MX5-7	56
MX5-6	57
MX5-5	58
MX5-4	59
LIN	60
RS232-RX	61
Ground	62
MX5-1	63
Ground	64
Ground	65
MX6-8	66
MX6-4	67
MX6-5	68
Supply of power outputs	69
Ground	70

## JetControlMobile 529

#### **Product brief**

In JCM-529, circuit parts for modular expansion of the JCM-521 series have been translated into a concept comprising fixed I/O configuration. This makes it a cost-effective solution keeping up the performance features of the JCM-521 series. Layoutreuse technology enables adjustments to be made in PCB assembly at low cost. 103 I/O connections are available in the fully equipped configuration.

An optional diagnostics display with controls features production data display, diagnostics and configuration on the spot without additional supporting devices such as PC or testing devices still being needed.

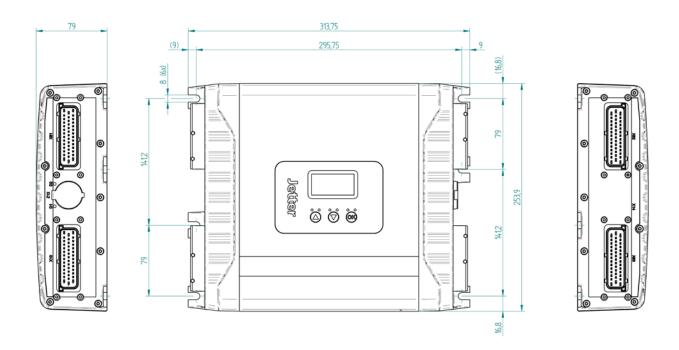
- 32-bit controller, 500 MHz
- Programming to IEC 61131-3 STX or in C/C++
- Fixed I/O configuration featuring modularizing varieties
- CAN, LIN, Ethernet and RS232 port for high connectivity
- Built-in controls with graphic display



	JetControlMobile 529	
CPU	ARM 11, 32-bit, 500 MHz	
Memory: RAM - Application - Non-volatile	64 MB RAM – 512 MB Flash – 64 kB MRAM	
Peripherals	FPGA	
Programming	IEC 61131-3 STX, C/C++	
Operating system	WinCE 6.0	
Operating voltage	DC 8 30 V, separate load voltage	
Operating/storage temperature	-40 +85 °C	
Ports and interfaces		
■ Ethernet	1 Up to 100 Mbit/s	
■ CAN	125 kB/s to 1 MB/s CANopen®, SAE J1939, ISOBUS 11783 Jetter CAN-Prim for customer-specific proprietary protocols	
■ RS232	1	
- LIN	4	
Operation and diagnostics (optional)	1 LCD graphics display 6 LEDs red, green 3 Keys	
RTC	Option	
Amount of inputs/outputs	103	
Inputs		
Analog	<ul> <li>0 5.7 V/0 15 V/0 20 mA, can be configured individually, capable of diagnostics Resolution: 12-bit, input impedance: 50 100 kΩ, load resistor: 120 Ω</li> <li>Alternative usage: <ul> <li>NAMUR input with a bias voltage of 8.2 V</li> <li>Digital input active-high, input impedance 50 100 kΩ</li> <li>Frequency input 0.1 10 kHz, period &gt; 1 μs, input impedance 50 100 kΩ</li> <li>Input for gate time measuring 0.1 10 s</li> <li>Interruptible input, 16-bit time stamp, resolution 1 μs</li> </ul> </li> </ul>	
Outputs		
■ PWM	<ul> <li>3,8 A; current control 1 %; 10 Hz 1 kHz Alternative usage: Digital output 3.5 A high-side</li> <li>3.5 A; current control 6 %; 10 Hz 1 kHz Alternative usage: Digital output 3.5 A high-side</li> <li>0,5 A; 10 Hz 1 kHz Alternative usage: Digital output 2,0 A high-side</li> </ul>	
■ H-bridge	3.5 A; current control 6 %; 10 Hz 1 kHz  2 Alternative usage:  4 4x digital output 3,8 A high-side  4x digital output 3,8 A low-side	
Max. permitted total current	40 A	
Diagnostics	Total current monitoring, protection against polarity reversal, overload and no- load detection, all I/Os are protected against short circuit to GND and Ub	
Degree of protection	IP65	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
	Yes	

# JetControlMobile 529

## Dimensional drawing



JVM-529	
AMP timer, 29-pin - Power	
Power supply - Emergency stop 1	1
Signal - Emergency stop 1	2
Ignition ON	3
LIN1	4
CAN1_IN_H	5
CAN1_IN_L	6
PWM low-current 1	7
Input 1	8
PWM low-current 2	9
Input 2	10
PWM low-current 3	11
Input 3	12
PWM low-current 4	13
Input 4	14
RS232_TXD	15

JVM-529	
AMP timer, 29-pin - Power	
RS232_RXD	16
CAN1_OUT_H	17
CAN1_OUT_L	18
TBC_OFF	19
PWM low-current D1	20
Power supply - Logic unit	21
Power supply	22
Power supply	23
Power supply	24
Power supply	25
Ground	26
Ground	27
Ground	28
Ground	29

JVM-529	JVM-529	JVM-529	
AMP timer, 42-pin - Group A	AMP timer 42-pin - Group B	AMP timer 42-pin - Group C	
H-bridge 1_B	Sensor supply 1	Sensor supply 1	1
H-bridge 2_B	Input 22	Input 42	2
Input 5	Input 23	Input 43	3
Input 6	PWM 6	Input 44	4
PWM precision current measuring 1	PWM 7	Input 45	5
PWM precision current measuring 2	PWM 8	Input 46	6
PWM precision current measuring 3	PWM 9	Input 47	7
Sensor supply 3	Input 24	Input 48	8
Input 7	Input 25	Input 49	9
Input 8	Input 26	Input 50	10
Input 9	Input 27	PWM 17	11
Input 10	Input 28	PWM 18	12
PWM 1	Input 29	PWM 19	13
Ground	Ground	Ground	14
H-bridge 2_A	Sensor supply 2	Sensor supply 2	15
Input 11	Input 30	PWM 20	16
PWM precision current measuring 4	PWM 10	PWM 21	17
PWM 2	H-bridge 3_A	Input 51	18
Sensor supply 1	H-bridge 3_B	Input 52	19
Sensor supply 2	H-bridge 4_A	Input 53	20
Input 12	H-bridge 4_B	Input 54	21
Input 13	Input 31	PWM 22	22
Input 14	Input 32	PWM 23	23
Input 15	Input 33	PWM 24	24
PWM 3	Input 34	PWM 25	25
PWM 4	Input 35	PWM 26	26
PWM 5	Input 36	PWM 27	27
Ground	Ground	Ground	28
H-bridge 1_A	Sensor supply 3	Sensor supply 3	29
Input 16	Input 37	PWM 28	30
Input 17	PWM 11	PWM 29	31
Input 18	PWM 12	Input 55	32
Input 19	PWM 13	Input 56	33
Input 20	Input 38	Input 57	34
Input 21	Input 39	Input 58	35
Power supply - Emergency stop 2	Input 40	PWM 30	36
Signal - Emergency stop 2	Input 41	PWM 31	37
UON_EXT	PWM 14	PWM 32	38
LIN2	PWM 15	PWM 33	39
CAN2_H	PWM 16	PWM 34	40
CAN2_L	LIN3	LIN4	41
Ground	Ground	Ground	42

# MX modules\_

#### **Product brief**

MX modules are configurable multi-purpose add-on modules for the JCM-511 and -521 controllers.

### Available configurations

- Multi-purpose 8-channel input module with analog/digital mode, current measuring and frequency measuring mode
- 8-channel output module
- 4-channel H-bridge module
- 8-fold output module with precision current measuring mode
- 2-channel weighing module with tilt sensor



	MX-MFQE	MX-DOUT8
Operating voltage; load voltage isolated	DC 8 32 V	DC 8 32 V, yes
Operating/storage temperature	-40 +85 °C	-40 +85 °C
Diagnostics	NAMUR	Open load, short circuit, current measuring
Max. amount of inputs/outputs	8	8
Inputs	Multifunction input	
<ul><li>Analog</li></ul>	0 5.7 V; 015 V; 0 22 mA	-
<ul><li>Digital</li></ul>	Active high	-
<ul><li>Frequency</li></ul>	0.1 10 kHz, period > 1 μs	-
Outputs		H-side
■ Digital; PWM	-	3.5 A (10 Hz 1 kHz, resolution 10 bits)
■ H-bridge	-	-
<ul><li>Analog</li></ul>	-	-
Max. total current	-	32 A
Safety relay in the load circuit	-	Yes
Vibration	DIN EN 60068-2-64, Cat. 2	DIN EN 60068-2-64, Cat. 2
Shock	DIN EN 60068-2-64, 30 g	DIN EN 60068-2-64, 30 g
Protection against polarity reversal	Yes	Yes

	MX-DOUT8P	MX-DOUT4HB	MX-RELAIS_S4
Operating voltage; load voltage isolated	DC 8 32 V, yes	DC 8 32 V, yes	DC 8 32 V, yes
Operating/storage temperature	-40 +85 °C	-40 +85 °C	-40 +85 °C
Diagnostics	Open load, short circuit; Precision current measuring (1 %)	Open load, short circuit, current measuring	n.a.
Max. amount of inputs/outputs	8	4	4
Inputs			
<ul><li>Analog</li></ul>	-	-	-
<ul><li>Digital</li></ul>	-	-	-
<ul><li>Frequency</li></ul>	-	-	-
Outputs	H-side, precision controlling	H-side/L-side, alternative: Individual PWM	Electrically isolated relays, NO contact
Digital; PWM	3.5 A (10 Hz 1 kHz, resolution 10 bits)		32 V/400 mA
H-bridge	-	3.5 A (10 Hz 1 kHz, resolution 10 bits)	-
<ul><li>Analog</li></ul>	-	-	-
Max. total current	32 A	32 A	4x 400 mA, not short-circuit proof
Safety relay in the load circuit	Yes	Yes	-
Vibration	DIN EN 60068-2-64, Cat. 2	DIN EN 60068-2-64, Cat. 2	DIN EN 60068-2-64, Cat. 2
Shock	DIN EN 60068-2-64, 30 g	DIN EN 60068-2-64, 30 g	DIN EN 60068-2-64, 30 g
Protection against polarity reversal	Yes	Yes	No

# JetControlMobile 350-E01 | E02 \_\_\_\_\_

#### **Product brief**

The controller JCM-350 was designed for control systems of a high total current. It can be obtained as variant -E01 featuring a maximum current of 106 A, or as variant -E02 with a maximum current of 212 A.

All outputs are rated at high currents. Further, the permitted inrush currents amount to a multiple of the rated currents. For this reason, the JCM-350 can be recommended for lighting systems or as body controllers for smart controlling of all electrical consumers of a vehicle according to demand.

High-performance H-bridges enable direct power supply of actuators, fans, heating systems or windscreen wipers.

5 independent CAN ports allow for integrating all CAN nodes of a vehicle. In this case, the controller acts as a CAN gateway. As an option, an operator interface can be built into the enclosure as well. It will report the operating states.

- 32-bit controller, 500 MHz
- Programming to IEC 61131-3 STX
- High single currents and high total current capacity
- High-performance H-bridges enable electric motor control
- 5 CAN ports
- Built-in operator interface

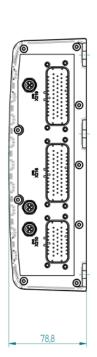


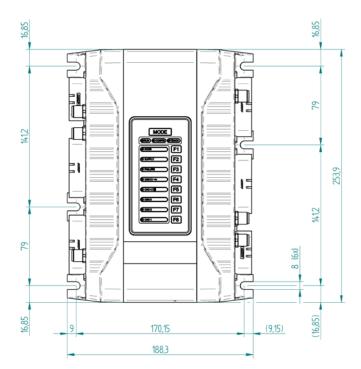
	JetControlMobile 350-E01   E02	
CPU	32-bit, 150 MHz	
Memory: RAM - Application - Non-volatile	16 MB RAM – 16 MB flash – 32 kB MRAM	
Programming	IEC 61131-3 STX	
Operating system	Jetter	
Operating voltage	DC 8 32 V, load voltage isolated	
Operating/storage temperature	-40 +85 °C	
Ports and interfaces		
■ CAN	125 kB/s to 1 MB/s 5 CANopen®, SAE J1939, ISOBUS 11783 Jetter CAN-Prim for customer-specific proprietary protocols	
Operation and diagnostics	11 status LEDs, dual-color red/green 9 keys	
Diagnostics	Total current monitoring, protection against polarity reversal, overload and no- load detection, all I/Os are protected against short circuit to GND and Ub	
Degree of protection	IP65	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	

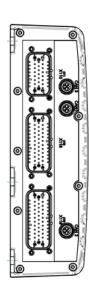
Variant	E01	E02	
Max. number of inputs/outputs	37	74	
Inputs			
<ul><li>Analog</li></ul>	4	8	$0\dots10 V\!/\!0\dots32 V\!/\!0\dots20$ mA/4 $\dots$ 20mA, can be configured individually, resolution: 12 bit, input impedance: $35~k\Omega$ , load resistor: $400~\Omega$
<ul><li>Digital</li></ul>	11	22	Active low/high, can be configured individually, Input impedance 3.2 $k\Omega$
<ul><li>Frequency</li></ul>	4	8	Active-low with pull-down resistor 0 50 kHz, input impedance 3.2 k $\Omega$
Outputs			
<ul><li>Analog</li></ul>	4	8	$0\ldots10V/0\ldots32V$ , can be configured individually, peak current 100 mA per output
<ul><li>Digital</li></ul>	8	16	8 A (16 A for 4 sec/40 A for 500 msec) Total current of each of the 4 digital outputs: 16 A
■ PWM	8	16	2 A (4 A for 4 sec/10 A for 500 msec) 25 Hz 1 kHz, without current control Total current of each of the 8 digital outputs: 8 A
H-bridge	2	4	16 A (32 A for 4 sec/80 A for 500 msec)
Relay			
High current	2	4	15 A
Standard design	2	4	2 A
Max. permitted total current	106 A	212 A	

# JetControlMobile 350-E01 | E02 \_\_\_\_\_

## Dimensional drawing







JCM-350*		
AMPSEAL Automotive Plug Connector 60874422		
Relay 1 (high current): shared contact	1	
Relay 2 (high current): NC contact	2	
Relay 2 (high current): NO contact	3	
Relay 2 (high current): shared contact	4	
Relay 3 (standard): shared contact	5	
Relay 3 (standard): NC contact	6	
Relay 4 (standard): NC contact	7	
Relay 3 (standard): NO contact	8	
Relay 1 (high current): NO contact	9	
Analog output 3	10	
Analog output 4	11	
PWM output 7	12	

JCM-350*		
AMPSEAL Automotive Plug Connector 60874422		
PWM output 8	13	
Relay 4 (standard): NO contact	14	
Relay 4 (standard): shared contact	15	
Relay 1 (high current): NC contact	16	
Ground	17	
Power supply - Digital peripherals	18	
Frequency/pulse input 3	19	
Frequency/pulse input 4	20	
Unused	21	
Unused	22	
Unused	23	

<sup>\*</sup> Note: The amount of connectors doubles in analogy with double assembly of the JCM-350-E02.

JCM-350*	
AMPSEAL Automotive Plug Connector 6	0874424
Digital output 6, current-sourcing	1
Power supply - Digital outputs 5 8	2
Power supply - Digital outputs 5 8	3
Bridge output 1, right	4
Bridge output 1, left	5
Power supply - Bridge 1	6
Power supply - Bridge 1	7
Bridge output 2, right	8
Bridge output 2, left	9
Power supply - Bridge 2	10
Power supply - Bridge 2	11
Frequency input 1	12
Digital output 5, current-sourcing	13
Digital output 8, current-sourcing	14
Bridge output 1, right	15
Bridge output 1, left	16
Ground	17
Ground	18
Bridge output 2, right	19
Frequency input 2	20
Bridge output 2, left	21
Digital input 11	22
Digital input 10	23
Digital output 7, current-sourcing	24
Digital input 4	25
Digital input 5	26
Digital input 6	27
Ground	28
Ground	29
Digital input 7	30
Digital input 8	31
Digital input 9	32
Not to be used (connector coding)	33
PWM output 5	34
PWM output 6	35

^   · · · · · · · · · · · · · · ·	1
Analog input 4	1
Analog input 3	2
Digital input 3	3
Digital input 2	4
Digital input 1	5
Digital output 2, current-sourcing	6
Digital output 4, current-sourcing	7
Digital output 1, current-sourcing	8
Digital output 3, current-sourcing	9
Power supply - Digital outputs 1 4	10
Power supply - Digital outputs 1 4	11
Power supply - Logic unit and peripheral devices	12
Analog input 2	13
Analog input 1	14
Analog output 1	15
Analog output 2	16
Ground	17
Ground	18
Power supply - Analog outputs	19
Ground	20
Power supply - PWM outputs	21
Power supply - Analog peripherals	22
Power supply - Digital inputs	23
PWM output 1	24
PWM output 2	25
PWM output 3	26
PWM output 4	27
Ground	28
Ground	29
CAN-L, CAN port 5	30
Power supply - Analog peripherals	31
CAN-L, CAN port 4	32
Do not connect	33
CAN-H, CAN port 4	34
CAN-H, CAN port 5	35

<sup>\*</sup> Note: The amount of connectors doubles in analogy with double assembly of the JCM-350-E02.

## JetControlMobile 350-E03 \_\_\_\_\_

#### **Product brief**

The large number of individually configurable I/O connections, the high total current as well as the rugged and compact design make the JCM-350-E03 a perfect controller for general control tasks.

The JCM-350-E03 comprises the remote I/O node JXM-IO-E02, as well as a controller board. Both components communicate via a CANopen® interface which can be addressed from the outside.

The CAN ID of the I/O node can be defined via external connection to digital inputs. This way, up to nine JXM-IO-E02 can be addressed within one system without further configuration measures to be taken.

The supply voltage of the inputs and outputs is divided into Standard Feed and Protected Feed, and it allows for independent deactivation of inputs and outputs in safety applications.

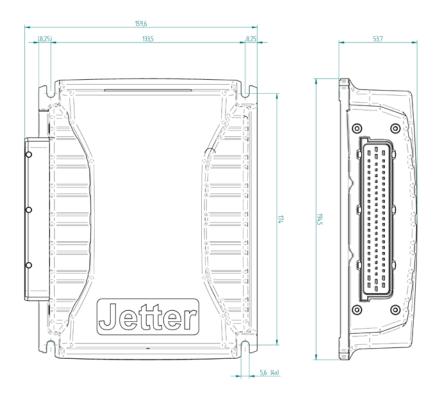
- 32-bit controller, 500 MHz
- Programming to IEC 61131-3 STX
- Flexible I/O configuration
- The CAN addresses can be configured via wiring harness
- Compact and rugged enclosure
- High degree of protection IP66/IP68



	JetControlMobile 350-E03	
CPU	32-bit, 150 MHz	
Memory: RAM - Application - Non-volatile	16 MB RAM – 16 MB flash – 32 kB MRAM	
Programming	IEC 61131-3 STX	
Operating system	Jetter	
Operating voltage	DC 8 32 V, load voltage isolated	
Operating/storage temperature	-40 +85 °C	
Ports and interfaces		
- CAN	125 kB/s to 1 MB/s 1 (optional 2) CANopen®, SAE J1939, ISOBUS 11783 Jetter CAN-Prim for customer-specific proprietary protocols	
RTC	Option	
Max. number of inputs/outputs	32	
Inputs		
<ul><li>Analog</li></ul>	4 0 5 V/0 Ub/0 20 mA/4 20 mA, can be configured individually, resolution: 10-bit, input impedance: 50 k $\Omega$ , load resistor: 240 $\Omega$	
■ Digital	Active low/high, can be configured individually, Input impedance 2 $k\Omega$	
■ Frequency	Active low/high, can be configured individually, 5 Hz 20 kHz, period 62.5 ns  2  Alternative usage:  Digital input active-high, input impedance 2 kΩ	
Outputs		
■ Analog	0 Ub, 10-bit resolution, short-circuit detection, peak current 100 mA	
<ul><li>Digital</li></ul>	<ul> <li>2.5 A high-side, diagnostics capability, short-circuit proof         Alternative usage:         <ul> <li>Digital input active-high, input impedance 100 kΩ</li> </ul> </li> <li>2 2.5 A high-side, diagnostics capability, short-circuit proof, supplied via Protected Feed         <ul> <li>Alternative usage:</li> <li>Digital input active-high, input impedance 100 kΩ</li> </ul> </li> <li>5 A high-side, diagnostics capability, short-circuit proof, supplied via Protected Feed         <ul> <li>Alternative usage:</li> <li>Digital input active-high, input impedance 100 kΩ</li> </ul> </li> </ul>	
■ PWM	2.5 A, max. 2 kHz, resolution: 8 bits, current-controlled, capable of diagnostics  Alternative usage: Digital output 2.5 A	
■ H-bridge	2.5 A  1 Alternative usage: 2 x digital output, 2.5 A	
<ul><li>Power supply</li></ul>	1 5 V power supply for sensors	
Max. permitted total current	40 A	
Degree of protection	IP66/IP68	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	
- Januar polarity 10101001		

# JetControlMobile 350-E03 \_\_\_\_\_

# Dimensional drawing



JCM-350-E03	
70-pin male AMPTyco connector	
Power supply - Protected Feed	1
Ignition ON	2
Digital In 1 - Standard Feed	3
Digital In 2 - Standard Feed	4
Digital In 3 - Standard Feed	5
Digital In 4 - Standard Feed	6
Digital In 5 - Standard Feed	7
Digital In 6/Out 1 - Standard Feed*	8
Digital In 7/Out 2 - Standard Feed*	9
Digital In 8/Out 3 - Standard Feed*	10
Digital In 9/Out 4 - Standard Feed*	11
Digital In 10/Out 5 - Standard Feed*	12
Digital In 11/Out 6 - Standard Feed*	13
Digital In 12/Out 7 - Standard Feed*	14
Digital In 13/Out 8 - Standard Feed*	15
Digital In 14/Out 9 - Protected Feed*	16
Digital In 15/Out 10 - Protected Feed*	17
Digital In 16/Out 11 - Protected Feed*	18
Digital In 17/Out 12 - Protected Feed*	19
Digital In 18/Out 13 - Protected Feed*	20
Digital In 19/Out 14 - Protected Feed*	21
Digital In 20/Out 15 - Protected Feed*	22
Digital In 21/Out 16 - Protected Feed*	23
Power supply - Standard Feed	24
Ground	25
Ground (analog IN 1)	26
Ground (analog IN 2)	27
Ground (analog IN 3)	28
Ground (analog IN 4)	29
Switch reference 1 *	30
Switch reference 2 *	31
Ground (digital Out 1)	32
Ground (digital Out 2)	33
Ground (digital Out 3)	34
Ground (digital Out 4)	35

70-pin male AMPTyco connector	
Ground (digital Out 5)	36
Ground (digital Out 6)	37
Ground (digital Out 7)	38
Ground (digital Out 8)	39
Ground (digital Out 9)	40
Ground (digital Out 10)	41
Ground (digital Out 11)	42
Ground (digital Out 12)	43
Ground (digital Out 13)	44
Ground (digital Out 14)	45
Ground (digital Out 15)	46
Ground (digital Out 16)	47
Ground	48
Analog 1 - In 1 - Standard Feed	49
Analog 2 - In 2 - Standard Feed	50
Analog 3 - In 3 - Standard Feed	51
Analog 4 - In 4 - Standard Feed	52
Analog Out - Standard Feed	53
Frequency In 1 - Standard Feed	54
Frequency In 2 - Standard Feed	55
PWM Out 1 - Standard Feed*	56
PWM Out 2 - Standard Feed*	57
PWM Out 3 - Standard Feed*	58
Ground (PWM 1)	59
Ground (PWM 2)	60
Ground (PWM 3)	61
CAN A Lo	62
CAN A Hi	63
CAN B Lo	64
CAN B Hi	65
5 V+ output ***	66
Node ID input 1	67
Node ID input 2	68
H-brigde A - Standard Feed*	69
H-brigde B - Standard Feed*	70

\* max. current 2.5 A

\*\* max. current 5 A

\*\*\* max. current 0.2 A

The maximum total current is 20 A per supply voltage type (Protected Feed, Standard Feed).

# Expansion modules \_\_\_\_\_



I/O modules providing a wide range of features let you in the best possible way complete or expand the control systems in mobile machinery, commercial and special-purpose vehicles.



# JXM-IO-E02

#### **Product brief**

The large number of individually configurable I/O connections, the high total current as well as the rugged and compact design make the JXM-IO-E02 a multi-purpose CAN remote node.

The supply voltage of the inputs and outputs is divided into Standard Feed and Protected Feed, and it allows for independent deactivation of inputs and outputs in safety applications.

The CAN-ID of the I/O node can be defined via external connection of digital inputs. This way, up to nine nodes can be addressed within one system without further configuration measures to be taken.

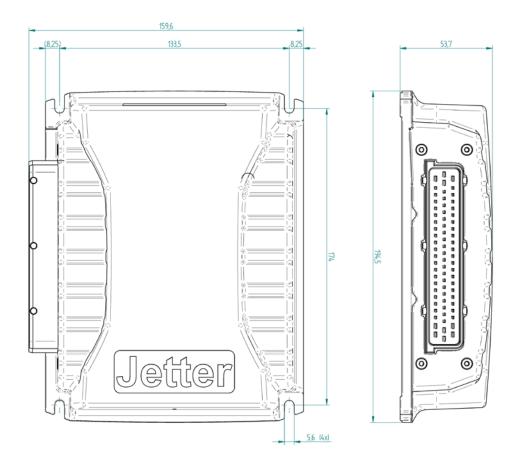
- Flexible I/O configuration
- The CAN addresses can be configured via wiring harness
- Compact and rugged enclosure
- High degree of protection IP66/IP68



	JXM-IO-E02	
Operating voltage	DC 8 32 V, load voltage isolated	
Operating/storage temperature	-40 +85 °C	
Ports and interfaces		
CAN	1 CANopen®	
Max. number of inputs/outputs	32	
Inputs		
<ul><li>Analog</li></ul>	4 0 5 V/0 Ub/0 20 mA/4 20 mA, can be configured individually, resolution: 10-bit, input impedance: 50 k $\Omega$ , load resistor: 240 $\Omega$	
■ Digital	Active low/high, can be configured individually, Input impedance 2 $k\Omega$	
Frequency	Active low/high, can be configured individually, 5 Hz 20 kHz, period 62.5 ns  2  Alternative usage:  Digital input active-high, input impedance 2 kΩ	
Outputs		
<ul><li>Analog</li></ul>	1 0 Ub, 10-bit resolution, short-circuit detection, peak current 100 mA	
■ Digital	<ul> <li>2.5 A high-side, diagnostics capability, short-circuit proof         Alternative usage:         <ul> <li>Digital input active-high, input impedance 100 kΩ</li> </ul> </li> <li>2.5 A high-side, diagnostics capability, short-circuit proof         <ul> <li>Alternative usage:</li> <li>Digital input active-low, input impedance 100 kΩ</li> </ul> </li> <li>5 A high-side, diagnostics capability, short-circuit proof, supplied via Protected Feed         <ul> <li>Alternative usage:</li> <li>Digital input active-high, input impedance 100 kΩ</li> </ul> </li> </ul>	
■ PWM	2.5 A, max. 2 kHz, resolution: 8 bits, current-controlled, capable of diagnostics  Alternative usage: Digital output 2.5 A	
H-bridge	1 2.5 A	
Power supply	1 5 V power supply for sensors	
Max. permitted total current	40 A	
Degree of protection	IP66/IP68	
Vibration	DIN EN 60068-2-64, Cat. 2	
Shock	DIN EN 60068-2-64, 30 g	
Protection against polarity reversal	Yes	

# JXM-IO-E02

# Dimensional drawing



JXM-IO-E02	
70-pin male AMPTyco connector	
Power supply - Protected Feed	1
Ignition ON	2
Digital In 1 - Standard Feed	3
Digital In 2 - Standard Feed	4
Digital In 3 - Standard Feed	5
Digital In 4 - Standard Feed	6
Digital In 5 - Standard Feed	7
Digital In 6/Out 1 - Standard Feed*	8
Digital In 7/Out 2 - Standard Feed*	9
Digital In 8/Out 3 - Standard Feed*	10
Digital In 9/Out 4 - Standard Feed*	11
Digital In 10/Out 5 - Standard Feed*	12
Digital In 11/Out 6 - Standard Feed*	13
Digital In 12/Out 7 - Standard Feed*	14
Digital In 13/Out 8 - Standard Feed*	15
Digital In 14/Out 9 - Protected Feed*	16
Digital In 15/Out 10 - Protected Feed*	17
Digital In 16/Out 11 - Protected Feed*	18
Digital In 17/Out 12 - Protected Feed*	19
Digital In 18/Out 13 - Protected Feed*	20
Digital In 19/Out 14 - Protected Feed*	21
Digital In 20/Out 15 - Protected Feed*	22
Digital In 21/Out 16 - Protected Feed*	23
Power supply - Standard Feed	24
Ground	25
Ground (analog IN 1)	26
Ground (analog IN 2)	27
Ground (analog IN 3)	28
Ground (analog IN 4)	29
Switch feed output 1 *	30
Switch feed output 2 *	31
Ground (digital Out 1)	32
Ground (digital Out 2)	33
Ground (digital Out 3)	34
Ground (digital Out 4)	35

JXM-IO-E02	
70-pin male AMPTyco connector	
Ground (digital Out 5)	36
Ground (digital Out 6)	37
Ground (digital Out 7)	38
Ground (digital Out 8)	39
Ground (digital Out 9)	40
Ground (digital Out 10)	41
Ground (digital Out 11)	42
Ground (digital Out 12)	43
Ground (digital Out 13)	44
Ground (digital Out 14)	45
Ground (digital Out 15)	46
Ground (digital Out 16)	47
Ground	48
Analog 1 - In 1 - Standard Feed	49
Analog 2 - In 2 - Standard Feed	50
Analog 3 - In 3 - Standard Feed	51
Analog 4 - In 4 - Standard Feed	52
Analog Out - Standard Feed	53
Frequency In 1	54
Frequency In 2	55
PWM Out 1 - Standard Feed*	56
PWM Out 2 - Standard Feed*	57
PWM Out 3 - Standard Feed*	58
Ground (PWM 1)	59
Ground (PWM 2)	60
Ground (PWM 3)	61
CAN A Lo	62
CAN A Hi	63
CAN B Lo	64
CAN B Hi	65
5 V+ output ***	66
Node ID input 1	67
Node ID input 2	68
H-brigde A - Standard Feed*	69
H-brigde B - Standard Feed*	70

\* max. current 2.5 A

\*\* max. current 5 A

\*\*\* max. current 0.2 A

The maximum total current is 20 A per supply voltage type (Protected Feed, Standard Feed).

# JXM-IO-E09

#### **Product brief**

The expansion module JXM-IO-E09 was designed as a high-current CAN node. It is for controlling power consumers such as spotlights or signal encoders in CANopen® networks.

Due to its small size, the module can be placed very flexibly very close to the consumer.

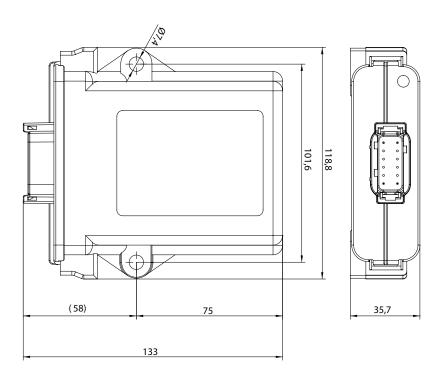
### **Product features**

- Rugged and compact enclosure
- High degree of protection IP67
- High total current
- CAN port



	JXM-IO-E09
Operating voltage	DC 8 32 V
Operating/storage temperature	-40 +85 °C
Ports and interfaces	
■ CAN	1 CANopen®
Outputs	
■ Digital	4 7.5 A high-side with current measuring, diagnostics capability, short-circuit proof
Max. permitted total current	30 A
Degree of protection	IP65/IP67
Vibration	DIN EN 60068-2-64, Cat. 2
Shock	DIN EN 60068-2-64, 30 g
Protection against polarity reversal	Yes

# Dimensional drawing



## Connector pinout

JXM-IO-E09	
DEUTSCH DTM13-12 PA-R008	
Power supply	1
Power supply	2
Power supply	3
Ground	4
CAN_H	5
CAN_H	6
Output 1	7
Output 2	8
CAN_L	9
CAN_L	10
Output 3	11
Output 4	12

Note: Load ground return via car body respectively individual grounding cable.

# JXM-IO-E11 \_\_\_\_\_

#### **Product brief**

The expansion module JXM-IO-E11 has been designed for signal processing in the dashboard or in the driver's cabin.

20 digital switching signals, 3 analog joystick axes and a 4-way switch can be combined to be transmitted to the controller as a CAN message.

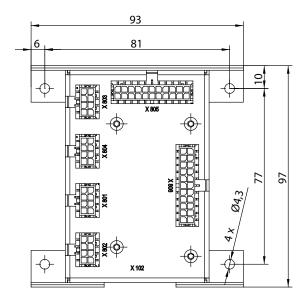
Up to 24 LEDs can be controlled via CAN in parallel. Out of these, 20 LEDs can be dimmed individually. This way, a balanced background lighting within the HMI can be set, even if dissimilar light sources are used.

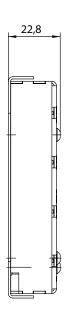
- Grouping of discrete input and output signals
- CANopen® port
- 5 V power supply, built in
- Compact design



	1)/04 10 544
	JXM-IO-E11
Operating voltage	DC 8 32 V
Operating/storage temperature	-40 +85 °C
Interface	
■ CAN	1 CANopen®
Max. number of inputs/outputs	50
Inputs	
<ul><li>Analog</li></ul>	0 5 V for analog joystick X-Y-Z, resolution 8 bits  Alternative usage:  4x digital input, 5 V, for b/w joystick
<ul><li>Digital</li></ul>	22 5 V for keys
Outputs	
■ PWM	20 5 mA for LEDs, resolution 4 bits
<ul><li>Digital</li></ul>	4 5 mA for LEDs
Degree of protection	IP20
Vibration	DIN EN 60068-2-64, Cat. 2
Shock	DIN EN 60068-2-64, 30 g
Protection against polarity reversal	Yes

## Dimensional drawing





# JXM-IO-E11 \_\_\_\_\_

## Connector pinout

4-way LED 4 Ground

JXM-IO-E11	
X801 CAN - Molex Microfit 8-pin	
Power supply	1
CAN-H_IN	2
CAN-H_OUT	3
CAN-L_IN	4
CAN-L_OUT	5
Ground	6
n.c.	7
Ground	8

JXM-IO-E11	
X803 4-way switch - Molex Microfit 8-pin	
Voltage output 5 V	1
4-way switch 3	2
4-way LED 3	3
Ground	4
Voltage output 5 V	5
4-way switch 4	6

8

JXM-IO-E11		
X802 joystick - Molex Microfit 8-pin		
n.c.	1	
Joystick x-axis or b/w, direction: north	2	
Joystick y-axis or b/w, direction: east	3	
Joystick z-axis or b/w, direction: south	4	
b/w, direction: west	5	
Joystick button 1	6	
Joystick button 2	7	
Ground	8	

JXM-IO-E11	
X804 4-way switch - Molex Microfit 8-pin	
Voltage output 5 V	1
4-way switch 1	2
4-way LED 1	3
Ground	4
Voltage output 5 V	5
4-way switch 2	6
4-way LED 2	7
Ground	8

JXM-IO-E11	
X805 switch inputs 1 to 16 - Molex Micro	ofit 22-pin
Voltage output 5 V	1
Switch 1	2
Switch 3	3
Switch 5	4
Switch 7	5
Switch 9	6
Switch 11	7
Switch 13	8
Switch 15	9
Ground	10
Ground	11
Switch 2	12
Switch 4	13
Switch 6	14
Switch 8	15
Switch 10	16
Switch 12	17
Switch 14	18
Switch 16	19
Ground	20
Ground	21
Ground	22

JXM-IO-E11	
X806 LED outputs 1 to 20 (dimmable	e)
Molex Microfit 22-pin	
Voltage output 5 V	1
Switch 1	2
Switch 3	3
Switch 5	4
Switch 7	5
Switch 9	6
Switch 11	7
Switch 13	8
Switch 15	9
Ground	10
Ground	11
Switch 2	12
Switch 4	13
Switch 6	14
Switch 8	15
Switch 10	16
Switch 12	17
Switch 14	18
Switch 16	19
Ground	20
Ground	21
Ground	22

## JXM-IO-E30 \_\_\_\_\_

#### **Product brief**

The expansion module JXM-IO-E30 is the universal building block for remote I/Os on mobile machinery. Thanks to its well-adjusted I/O configuration, it can take on almost any remote task and this way significantly reduce wiring expenses. The reference output lets you use standard sensors and carry out pre-processing applications.

Communication with the JXM-IO-E30 takes place via CANopen<sup>®</sup>. This allows for integration into conventional CAN networks used in mobile machinery.

Thanks to its potted - and thus rugged - housing the expansion module is applicable in any situation even under harsh environmental conditions.

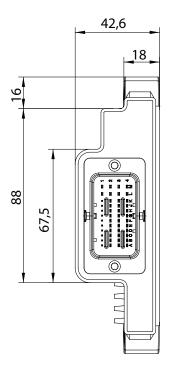
- 12 inputs and 14 diagnostics-capable outputs - including high current paths and PWM with current control
- High switching capacity thanks to parallel use of outputs and high continuous total current
- CAN ID addressing via tri-state inputs allows integration of up to nine nodes in one network without software configuration, and thus supports the common part strategy
- Short-circuit-proof sensor supplies
- Rugged, potted housing

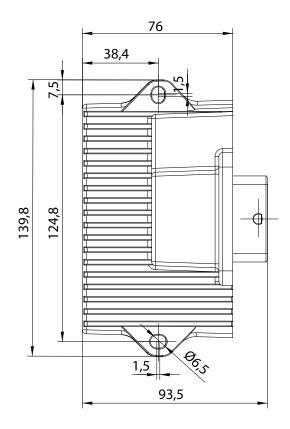


JXM-IO-E30
DC 8 32 V, with separate ECU power supply
-40 +85 °C
1 CANopen®
26
8 0 5 V/0 20 mA, can be configured individually, Resolution: 10 bits, input impedance: 35 k $\Omega$ , load resistor: 120 $\Omega$
<ul> <li>Active-high,</li> <li>input impedance 5.6 kΩ</li> <li>0.1 Hz 10 kHz</li> </ul>
2 Coding of the CAN ID, tristate
<ul> <li>3A, 1.5 kHz max., dithering, current-controlled, diagnostics capability, short-circuit proof</li> <li>Alternative usage:         <ul> <li>Digital input active-low, input impedance 10 kΩ</li> <li>Digital output 3 A</li> <li>PNP input</li> </ul> </li> </ul>
<ul> <li>7 A, 1.5 kHz max., dithering, diagnostics capability, short-circuit proof</li> <li>Alternative usage:         <ul> <li>Digital input active-low, input impedance 10 kΩ</li> <li>Digital output 7 A</li> <li>PNP input</li> </ul> </li> </ul>
3 A high-side, diagnostics capability, short-circuit proof, (with 50 % ON period)  4 Alternative usage:  Digital input active-low, input impedance 10 kΩ  PNP input
3 Independent Uop supply for sensors
25 A
IP65
ISO 16750-3
ISO 16750-3
150 16750-3
Yes

# JXM-IO-E30 \_\_\_\_

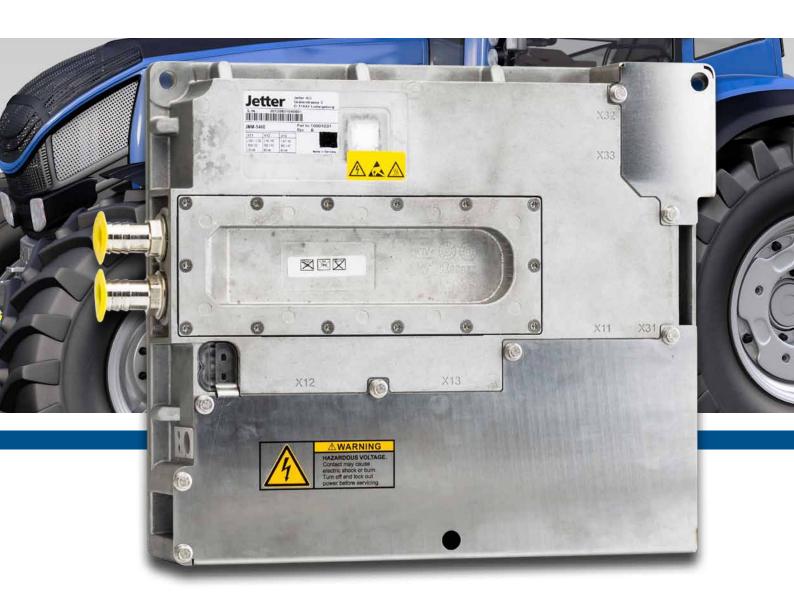
## Dimensional drawing





JXM-IO-E30	
CAN_H	A1
CAN_L	B1
HS3C_4	C1
HS3C_3	D1
HS3C_2	E1
HS3C_1	F1
HS3_4	G1
HS3_3	H1
HS3_2	J1
HS3_1	K1
UB	L1
UB	M1
CAN_TERM2	A2
CAN_TERM1	B2
DIP_1	C2
DIP_2	D2
DIP_3	E2
DIP_4	F2
SGND	G2
SPWR_3	H2
SPWR_2	J2
SPWR_1	K2
UB	L2
HS7_1	M2

JXM-IO-E30	
n.c.	A3
ANI_1	В3
ANI_2	C3
ANI_3	D3
ANI_4	E3
ANI_5	F3
ANI_6	G3
ANI_7	H3
ANI_8	J3
ECU_UB	K3
GND	L3
HS7_2	M3
HS7_5	A4
HS7_5	B4
HS7_6	C4
HS7_6	D4
HS7_4	E4
HS7_4	F4
HS7_3	G4
HS7_3	H4
IN_CFG1	J4
OUT_CFG2	K4
GND	L4
GND	M4



For electrification of drive systems, we provide highly-specialized and especially powerful and robust devices.



# JetMoveMobile 5000

#### **Product brief**

Servo amplifiers of the JetMoveMobile-5000 series are key to electrification of mobile machinery. Thanks to their high quality of control, these servo amplifiers achieve a significantly higher level of effectiveness than it is the case with comparable hydraulic motion systems. Decoupling the speed of the Diesel engine from the speed requirements of the processes enables the Diesel engine to run at its optimum operating point. This results in lower fuel consumption, sided by reduced noise emission.

Having got water-cooling, the inverter could be designed very compact. This allows for space-saving installation in the vehicle.

The enclosures of the servo amplifiers are both extremely rugged and protected according to IP6K9K (pressure washing).

## **Product features**

- Extremely rugged (IP6K9K)
- High quality of control
- Fast and safe processes
- High efficiency
- Reduces fuel consumption
- Low noise level
- Parallel operation of up to 80 kW
- Water-cooled
- Stackable

### **Options**

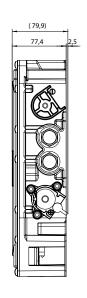
DC/DC converter up to 200 A

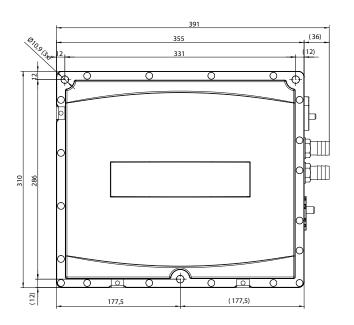


	JMM-5440-800
Power output stage 1 (Continuous output)	40 KW
Current	58 A <sub>RMS</sub>
Frequency	0 1000 Hz
Power output stage 2 (Continuous output)	40 KW
Current	58 A <sub>RMS</sub>
Frequency	0 1000 Hz
DC link voltage	DC 200 800 V
Operating voltage (logic unit)	DC 8 32 V
Operating/storage temperature	-40 +85 °C
Ports and interfaces	
- CAN	2
Max. amount of inputs/outputs	8
Inputs	
- Analog; digital; frequency	0, 4, (4)
Outputs	
- Digital; PWM; H-bridge	(4); 4; 0
Coolant, operating pressure	Water, 2 bar max.
Coolant, temperature (during operation)	30 65 °C
Degree of protection	IP6K9K
Vibration	DIN EN 60068-2-64, Cat. 2
Shock	DIN EN 60068-2-64, 30 g
Protection against polarity reversal	Yes

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

## Dimensional drawing





	JMM-5330-800	JMM-5220-800	JMM-5210-800	JMM-5201-800
Power output stage 1 (Continuous output)	20 KW	10 KW	10 KW	10 KW
Current	30 A <sub>RMS</sub>	15 A <sub>RMS</sub>	15 A <sub>RMS</sub>	15 A <sub>RMS</sub>
Frequency	0 1000 Hz	0 1000 Hz	0 1000 Hz	0 1000 Hz
Power output stage 2 (Continuous output)	20 KW	10 KW	5 KW	DC/DC converter
Current	30 A <sub>RMS</sub>	15 A <sub>RMS</sub>	8 A <sub>RMS</sub>	DC 14 V/200 A
Frequency	0 1000 Hz	0 1000 Hz	0 1000 Hz	DC
DC link voltage	DC 200 800 V			
Operating voltage (logic unit)	DC 8 32 V			
Operating/storage temperature	-40 +85 °C	-40 +85 °C	-40 +85 °C	-40 +85 °C
Ports and interfaces				
- CAN	2	2	2	2
Max. amount of inputs/outputs	8	8	8	8
Inputs				
- Analog; digital; frequency	0, 4, (4)	0, 4, (4)	0, 4, (4)	0, 4, (4)
Outputs				
- Digital; PWM; H-bridge	(4); 4; 0	(4); 4; 0	(4); 4; 0	(4); 4; 0
Coolant, operating pressure	Water, 2 bar max.			
Coolant, temperature (during operation)	30 65 °C	30 65 °C	30 65 °C	30 65 °C
Degree of protection	IP6K9K	IP6K9K	IP6K9K	IP6K9K
Vibration	DIN EN 60068-2-64, Cat. 2			
Shock	DIN EN 60068-2-64, 30 g			
Protection against polarity reversal	Yes	Yes	Yes	Yes

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# System components \_\_\_\_\_



The variety of functions and ease of operation are significantly increased by system components. Individual demands placed on user-friendly operation and configuration of mobile machinery can very easily be met this way.



# **POWERTRACK**

#### **Product brief**

POWERTRACK allows for HMIs to be expanded by a rotary encoder and 6 user-programmable keys. POWERTRACK connected via CAN enables intuitive and efficient user guidance.

#### **Product features**

- Easy-to-grip rotary encoder which can also be handled by a user wearing gloves
- 6 user-programmable keys which can be labeled individually
- Keys with multi-color LEDs for state reporting
- Compact design (degree of protection: IP54)
- CAN interface for CANopen® or SAE J1939 (option)



	POWERTRACK
Connector	Deutsch DT04-4P
Service life - keyboard	3 million switching cycles min.
Service life - rotary encoder (key function)	1 million switching cycles min.
Service life - rotary encoder (rotary function)	100,000 cycles min.
Keyboard	Silicone rubber, PU-hardcoated
Operating/storage temperature	-40 °C +70 °C / -40 °C +85 °C
UV radiation protection	UVB resistance: 400 hours
Salt spray	To ASTMB117
Chemical resistance	DEET, motor cleaners, isopropanol, sunscreen, multi-purpose cleaners, orange- or lemon-based cleaners
Degree of protection	IP54
Power supply	Rated voltage DC 12 24 V (DC 8 32 V)
Communications bus	CANopen <sup>®</sup>

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# POWERKEY PRO \_\_\_\_\_

#### **Product brief**

The keyboard series POWERKEY PRO excels by its compact design. Being equipped with a CAN interface and keys which can be assigned by the user, this device opens up a wide range of application options. Meeting specific requirements for the operation of mobile machinery can be very easy this way.

### **Product features**

- The keys are raised so they can even be easily pressed by operators wearing gloves.
- User-programmable keys. Layout 2x2, 3x2, 4x2, and 6x2
- Individually printable key caps, standard: > 100 icons
- Keys with multi-color LEDs for state reporting
- Compact design (degree of protection: IP67)
- CAN interface for CANopen® or SAE J1939 (option)



	POWERKEY PRO
Connector	Deutsch DT04-4P
Service life - keyboard	3 million switching cycles min.
Keyboard	Silicone rubber, PU-hardcoated
Operating/storage temperature	-40 °C +70 °C / -40 °C +85 °C
UV radiation protection	UVB resistance: 400 hours
Salt spray	To ASTMB117
Chemical resistance	DEET, motor cleaners, isopropanol, sunscreen, multi-purpose cleaners, orange- or lemon-based cleaners
Degree of protection	IP67
Power supply	Rated voltage DC 12 24 V (DC 8 32 V)
Communications bus	CANopen®

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

# JXM-CAM \_\_\_\_\_

#### **Product brief**

The JXM-CAM is a video camera especially designed for outdoor use. It is ideal for use as a surveillance camera in mobile machinery, or as a rear-view camera in cars.

When the light conditions turn weak the photo sensor automatically activates the infrared LEDs which completely illuminate a circle of 10 m in diameter.

The JXM-CAM can be used along with all devices by Jetter AG which are equipped with the corresponding video input.



#### **Product features**

Compact steel-sheet enclosure

Degree of protection: IP68

Operating voltage: DC 12 V

Ambient temperature: -30 ... +65 °C

	JXM-CAM
System	PAL/NTSC, automatic changeover
Operating voltage	DC 12 V
Operating/storage temperature	-30 +65 °C/-40 +80 °C
Input current	0.2 A
Outputs:	
- Video	1 (MiniDIN - Composite 1 Vp-p 75 ohms)
Degree of protection	IP68
Night-time operation	Infrared LEDs for illumination at night (sensor-controlled activation)
Dimensions (W x H x D)	90 x 80 x 55 mm

Further details and order information are available on request. Specifications are subject to change without notice. Errors and omissions excepted.

## Connector pinout

JXM-CAM	
5-pin MiniDIN connector	
Power DC 12 V (yellow)	1
Audio IN (red)	2
Mirror (blue)	3
Video IN (white)	4
GND	5

# Wiring harness | RAM Mount mounting bases

### **Product brief**

Design and manufacturing of wiring harnesses are a decisive factor for the functional reliability of mobile machinery. Customized wiring harnesses enable implementing customer-specific features. Jetter AG provides long-year expertise in wiring harness technology.

### **Product brief**

Dash mounts by RAM Mount allow quick and easy positioning of HMIs for the perfect angle.

For individual HMIs there are corresponding dash mounts and mounting solutions available.





Jetter AG software solutions unite simplicity and integration. A decisive factor in this case is the usability of the systems.



# **JetSym**

#### **Product brief**

JetSym is the central programming tool by Jetter AG compliant with IEC-61131-3. It corresponds to all technology functions needed for mobile machinery.

From programming the control system to commissioning the mobile machine, every programming detail can be realized with JetSym.

#### **Product features**

- Configuration
- Programming
- Debugging
- Commissioning
- Diagnostics
- Version management



## The programming language STX

STX meets all requirements of mobile machinery automation. Its syntax is based on IEC 61131-3 ST. With this process-oriented language, the real processes of a machine can be directly mapped and described. High-performance commands for PWM-controlled valve handling, motor control, operator interaction and strings make programming of controllers much easier.

The object-oriented approach of STX offers clear advantages. With it, tried and tested routines can be encapsulated so that neither the code nor the essential data can be changed.

In addition, classes can also take over data structures and methods of other classes and extend them. It is exactly this basic principle of object-oriented programming, which is highly interesting for automation systems: Here, the programmer can map shared object properties through a base class and therewith define derived classes for the different manifestations of the objects. The use of these program elements is especially efficient.

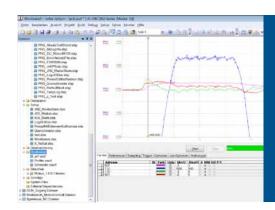
# Object orientation helps to reduce development and testing times

The object-oriented approach of STX helps to reduce development and testing times. With it, tried and tested routines can be encapsulated so that neither the code nor the essential data can be changed. Besides mere reusability, classes can also take over data structures and methods of other classes and extend them. It is exactly this basic principle of object-oriented programming, which is highly interesting for state-of-the-art software architecture in mobile machinery. Here, the programmer can map shared object properties through a base class and therewith define derived classes for the different manifestations of the objects/functions. The use of these program elements is especially efficient and significantly reduces testing times.

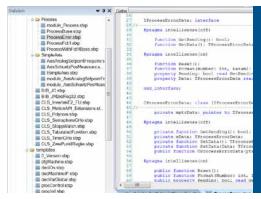
#### STX - Can do more

STX has been extended beyond the standard to include many important elements that are indispensable in modern automation. These include object orientation, which is integrated into STX to a very high degree. Many further indispensable functions can be mapped with simple and common commands:

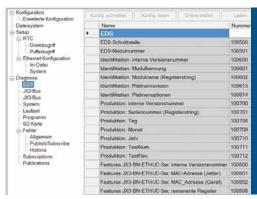
- Positioning
- CAN library
- Hydraulics temperature compensation by current regulation
- Task management
- File operations on the file system of the control system
- String processing
- Data processing in complex structures
- Exception handling
- and much more



Oscilloscope mode



Pragma INTELLISENSE(OFF)



EDS (Electronic data sheet)

# **JetViewSoft**

#### **Product brief**

The software tool JetViewSoft lets you easily visualize processes and design individual screens for HMIs. The proven object-oriented approach allows you to easily and efficiently complete even complex visualization tasks without previous experience. The user-friendly editor and a pool of predefined objects actively help you create screens in no time at all.

All important functions such as alarm handling, trending and libraries are available for the creation of sophisticated visualizations. The easy-to-use editor with its object-oriented approach helps you implement large projects in an easy and efficient way.



#### **Product features**

- Supports scalable vector graphics and SVG import
- Features gesture control for modern visualizations
- Efficient design process thanks to object-oriented structure
- Database with predefined objects and preview feature
- Supports creation of multilingual screens and import/export of language resources
- Alarm handling and trend graph
- STX as scripting language lets you add new functions
- Terminal Wizard and simple download to HMIs

#### Full scalability thanks to vector graphics technology

The vector graphics technology of JetViewSoft allows for complete and lossless scalability of all objects (except for bitmap graphics). Thus, projects or project parts that are designed for a specific resolution of the target device can be used on displays with a different resolution without any loss.

#### **SVG** import

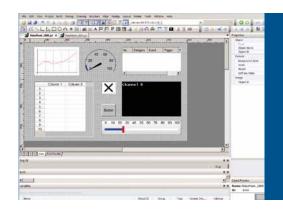
JetViewSoft lets you directly import SVG files from graphics or CAD tools into a visualization application. Cumbersome conversion of CAD drawings into bitmap format is therefore a thing of the past.

#### Object-oriented and efficient

The object-oriented approach of JetViewSoft makes generating screens a lot easier. Objects such as buttons need to be defined only once before they can be used as often as they are needed. Making changes to an object property automatically takes effect wherever this object has been applied. Various visualization objects can be dynamically displayed during runtime in the control program by means of pointers.

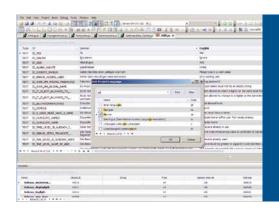
#### Configuring objects rather than programming

In JetViewSoft, visualizations can be configured using existing graphic objects. To this end, predefined objects, such as sliders, meters, buttons, lines, circles, ellipses, list boxes, check boxes, symbols, XY graphs, image and video objects are simply arranged by drag and drop in the development environment. These elements can be arranged one upon the other or side by side. They can also be combined to form groups. All elements can be stored in a separate structured object library.



### Editing and managing multilingualism in a central repository

In JetViewSoft, the selected language and optional image fonts are loaded from a central language management pool during runtime. This allows for simple import or export of language resources as CSV files for further editing in MS Excel, for instance. Translation, maintenance and handling of several languages can be carried out quickly and easily.



#### Macro and scripting language in perfect unison

For simple processes, JetViewSoft offers programmable macro functions. For complex processes, calculations, or for programming special functions, STX, a programming language based on IEC-61131-3, is available as scripting language. This scripting language is also used to program Jetter controllers. This means, JetViewSoft and STX stand for perfect compatibility.



# **ISO-Designer**

#### **Product brief**

With the ISO-Designer from Jetter AG, it is simple to create ISOBUS-compliant files. ISO-Designer commands a high-performance graphical editor with a functional scope comparable to graphic programs. Many actions can easily be executed by a few mouse clicks.

#### **Product features**

- Creating masks to ISO 11783 (.iop files)
- Graphics editor
- Convenient aligning/grouping
- Operating by drag-and-drop
- Zoom function
- Undo/redo function
- Configurable GUI
- Smart copy function
- Object pool with preview function
- Library
- Bookmarks and history
- Supporting standards on all levels
- Automatic color conversion
- Preview function
- Multilingualism is easy to implement



### We are members





#### Clearly designed project management | 100 % ISO-compliant

Optimum project management is achieved by presenting the objects in a clear tree structure with a preview function. The ISO-Designer supports all specified levels of the standard. When you create a new project, you are free to choose which specifications should apply. The automatic color space conversion of imported images always ensures compliance with the ISO standard.



Everything at a glance

#### Ease of operation leaves no wish unfulfilled

Profit from numerous convenient functions which ease your daily work. This way, even the work interface can be customized to your needs. All functions first go through an intensive practical test before they are finally integrated into the program.



Optimized for the practice

#### Multilingualism | More options

With the ISO-Designer, multilingual masks are especially simple to create. A resource file saves all the necessary information. The relevant texts are displayed depending on the active language. The resource file can also be exported as a table and imported again, which substantially simplifies external translation of the texts.



Fast, efficient language management



## ISO-Designer – Get your license at no cost for an unlimited period.

Register at www.iso-designer.de and you will receive your personal activation code. Profit from the benefits:

- Standard-compliant further development with update service
- Full functionality
- Full support
- Full compatibility for every ISOBUS terminal

# Professional Services \_\_\_\_\_



Jetter AG provide professional services for the entire field of mechanical and plant engineering. The choice is yours: You can have us manage your entire project or let us contribute our know-how for specific solutions.



### Our services at a glance:

- Consulting | Project management
- Controller programming services
- Creation of visualization applications
- Electrical engineering | Control cabinet production
- Service | Maintenance
- Training
- Retrofit

Take the easy option and let our experts advise you from the very start. As part of our project management process, we'll work with you to identify which system, which partial or complete solution with which device, best suits your needs.

# Consulting and management

- End-to-end project management
- Use of standard project management software
- Conceptual design and project planning (centralized, decentralized), dimensioning of project-specific drive technology
- Path, movement and energy optimization
- Selecting sensors, actuators and motors, as well as suitable automation components
- Procuring all necessary components

## Controller programming

- Structured text programming to IEC 61131-3-(ST)
- Conceptual design and development of software structures
- Development of programming concepts suitable for series production machinery including version management, update functions and variant handling
- Complete function test and acceptance

# Creation of visualization applications

- Visualization using your own or standard visualization software
- Implementation of database integration
- Selection and programming of suitable user interfaces with key, mouse or touch operation
- Complete function test and acceptance



# Electrical engineering and Control cabinet production

- Planning and optimizing production capacity
- Manufacturing control panels and cabinets
- Fabrication in accordance with current EN regulations
- Wire harness manufacturing
- CE certification with risk analysis
- Electrical design with Eplan
- Planning and design according to current standards
- Creating wiring, terminal and cable diagrams

# Service and maintenance

- Hotline | Telephone and e-mail support
- 24/7 stand-by support on request
- On-site repairs and replacements by our own service team
- On-line support with optional remote access
- Remote maintenance
- Compatibility analysis for products and systems
- Maintenance contracts | Preventative maintenance
- Optional enhanced warranty offers

## Training

- STX programming
- Drive technology/MC
- Visualization
- Service staff

## Retrofit

- Upgrading existing machines to create a modern, powerful control system
- Seamless integration with the existing IT structure
- Coordination of conversion work with non-production times



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